



**National Institute of Technology Meghalaya**  
An Institute of National Importance

**CURRICULUM**

Programme	<b>Bachelor of Technology</b>	Year of Regulation	<b>2018-19</b>
Department	<b>Mathematics</b>	Semester	<b>VII</b>

Course Code	Course Name	Pre-Requisite	Credit Structure				Marks Distribution			
			L	T	P	C	INT	MID	END	Total
<b>MA 471</b>	<b>Non-linear Optimization</b>	<b>MA 372</b>	<b>2</b>	<b>0</b>	<b>0</b>	<b>2</b>	<b>50</b>	<b>50</b>	<b>100</b>	<b>200</b>

Course Objectives	To provide fundamental understanding of nonlinear optimization.	Course Outcomes	<b>CO1</b>	Able to understand the concept of convex set and convex function, and to solve convex optimization problems.
			<b>CO2</b>	Able to verify optimality conditions and to apply to solve unconstrained optimization problems.
	<b>CO3</b>		Able to use Lagrange multipliers and Karush-Kuhn-Tucker conditions to solve constrained optimization problems	
	<b>CO4</b>			
	<b>CO5</b>			
	<b>CO6</b>			
To describe application of nonlinear optimization				

No.	COs	Mapping with Program Outcomes (POs)												Mapping with PSOs		
		PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
1	CO1	2				2										
2	CO2	2				2										
3	CO3	2				2										
4	CO4															
5	CO5															
6	CO6															

**SYLLABUS**

No.	Content	Hours	COs
I	<b>Convex Analysis:</b> Introduction to nonlinear programming problem, convex sets, convex functions, maxima and minima of convex function, Convex optimization problems	<b>06</b>	<b>CO1</b>
II	<b>Unconstrained optimization:</b> First-order and second-order optimality conditions, line search methods, method of steepest descent, Newton's method, conjugate direction method and quasi-Newton methods.	<b>09</b>	<b>CO2</b>
III	<b>Constrained optimization:</b> Equality and inequality constraints, method of Lagrange multipliers, Karush-Kuhn-Tucker conditions, Sensitivity Analysis; Quadratic Programming	<b>09</b>	<b>CO3</b>
<b>Total Hours</b>		<b>24</b>	

**Essential Readings**

1. M. S. Bazaara, H. D. Sherali and C. M. Shetty, “Nonlinear Programming: Theory and Algorithms”, Wiley India, 3<sup>rd</sup> edition, 2017.
2. E. K. P. Chong and S. H. Zak, “An Introduction to Optimization”, Wiley India, 4<sup>th</sup> edition, 2017.

**Supplementary Readings**

1. D. G. Luenberger and Yinyu Ye, “Linear and Nonlinear Programming”, Springer India, 3<sup>rd</sup> edition, 2010
2. F. S. Hillier, G. J. Lieberman, B. Nag and P. Basu, “Introduction to Operations Research”, 9<sup>th</sup> edition, McGraw Hill Education, 2009.