## National Institute of Technology Meghalaya

An Institute of National Importance

CURRICULUM

T. HONTON OF TECHNOLOGY		Dotalis	,																
	Progran														ar of Regul		2018		
	Departn	nent	Mec	hanical E	ingineerin	ıg					G 11			Se	emester	1 100	1	VII	
	urse ode	Course Name Credit Structure  L T P C												Marks Distribution Continuous Evaluation			Tota		
		ADVANCED MECHANICAL LAR.II (MECHATDONIC																	
ME 451		LABORATORY) U 1 2 2													100			100	
													dentify and understand the use and application of mechatronics components. (Understanding)						
Course Objectives							nachetroni	as actuato	re.		C	A	ble to use	the LabV	IEW softw	are for int			
		To familiarizes use of control module and mechatronics actuators.  CO2 application developme  Course  Able to utilize different														-			
		To familiarizes use of vision-based system for robotic application.  Outcomes  CO3   Able to use control mo Automation. (Applying)  Able to use vision base													nt sensors	for variou	s applica	tions.	
																mechatro	nic syste	m for	
															g) e robotic systems for different				
			CO5 Able to use vision base application. (Analysing																
No.	CO	s	Mapping with Program Outcomes (POs)													Mapping with PSOs			
			PO1	PO2	PO3	PO4	PO5	PO6	F		08	PO9	PO10	PO11	PO12	PSO1	PSO2	PSC	
2	CO		3	0	3	0	3	3		0	0	0	1 1	0	2 2	1	2	0	
3	CO		3	0	3	0	3	3		0	0	0	1	0	2	1	2	0	
4	CO	4	3	0	3	0	3	3		0	0	0	1	0	2	1	2	0	
5	CO	5	3	0	3	0	3	3		0	0	0	1	0	2	1	2	0	
lo.	SYLLABUS  Content														Hours COs				
																06		CO1	
Ι	Introduction to LabVIEW software and interfacing with different sensor module.													CO2					
II	differe	Microcontroller I/O and inter-device communication using industry standards such as SPI, I2C, and CAN buses with different Mechatronics Sensors: Strain gauge, Pressure transducer, Ultrasonic and Infrared sensor, Reflective optical sensor, Potentiometer.														06 CO1			
Ш	Experiment with Mechatronics Actuators: Brushed DC motor, Stepper motor, Servo motor.														06 CO1				
IV	Experiment with Control Module & Mechatronics Systems.														06 CO3				
V	Experiment with Smart Factory Automation System: Automatic Storage and Retrieval System, Automated Guided Vehicle.														I	06 CO3			
VI	Experiment with Vision Based Mobile Robotic kit.														06 CO5				
						,	Total Hou	re								36			
		eading					1 Otal 110U	10								30			

## **Essential Readings**

- 1. M. P. Groover, "Industrial Robotics Technology, Programming and Applications", McGraw-Hill, 2<sup>nd</sup> Edition, 2012.
- 2. K. S. Fu, R. C. Gonzalez and C.S.G. Lee, "Robotics Control, Sensing, Vision and Intelligence", McGraw-Hill, 1st Edition, 1987.

## **Supplementary Readings**

- 1. Y. Koren, "Robotics for Engineers", McGraw-Hill, 1st Edition 1985.
- 2. J. J. Craig, "Introduction to Robotics: Mechanics and Control", Pearson Education International, 3<sup>rd</sup> Edition, 2005.
- 3. M. W. Spong and M. Vidyasagar, "Robot Dynamics and Control", Wiley, 1st Edition, 2008.
- 4. R. J. Schilling, "Fundamentals of Robotics Analysis and Control", Prentice Hall of India Pvt. Ltd., 1st Edition, 1996